

AMENDMENTS TO THE SPECIFICATION:

Please amend the indicated paragraphs of the specification in accordance with the amendments indicated below.

Page 1: 2nd full paragraph, amend as indicated below:

There is an operation management system having a data recorder that records measured data of the behavior of vehicles and other mobile objects and a behavior analyzer that performs analysis of the measured data recorded on the data recorder. In such an operation management system, the data recorder, which detects measured data of behavior of vehicles and records data, is also referred to as a safety recorder ~~comprising and comprises~~ a sensor section ~~composed of~~ including an angular velocity meter, an accelerometer, a ~~[[GSP]]~~ GPS (Global Positioning System) receiver, and a recorder section for recording measured data detected by the sensor section. Measured data specifically includes angular velocity data including at least ~~[[of]]~~ data on roll, pitch, and yaw, and acceleration data of any one of first to three dimensions, GPS data indicative of latitude, longitude, velocity ~~[[,]]~~ and direction.

Page 2: 1st full paragraph, amend as indicated below:

In conventional systems, one data recorder is fixed to a target vehicle. Also, measured data is recorded regardless of who is a driver. In the case of an occurrence of an accident, ~~this is because~~ the conventional data recorder analyzes the behavior

of the vehicle ex post facto to investigate the cause of the accident. This extremely restricts the range of use of such systems and causes difficulty in the widespread use of such systems by ordinary to the general drivers.

A2 [Page 2: 2nd full paragraph, amend as indicated below:]

In conventional, all measured data generated in the behavior of vehicle is recorded. For this reason, the data recorder is required to reserve enormously large area for recording within a given time period in order to repeat the recording. The analyzer is required to execute heavy processing in order to discriminate measured data recorded.

[Pages 12 and 13: the paragraph bridging these pages, amend as indicated below:

A3 The sensor section 11 has angular velocity meters 111x, 111y, and 111z for detecting angular velocity data of three-dimensional axial direction (roll, pitch, and yaw) in the vehicle, accelerometers 112x and 112y for detecting acceleration data (accelerator acceleration, brake acceleration, cornering acceleration and like) in the back and fourth and right and left of the vehicle, and a [[GSP]] GPS (Global Positioning System) receiver 113 for receiving GPS data indicative of current latitude, longitude, velocity [[,]] and direction of the vehicle, and a pulse obtaining mechanism 114 for obtaining a vehicle velocity pulse from a vehicle instrument.